### **TDK Developer's Conference 2018**

Piezoelectric Haptics Actuators for High Force and High Acceleration Applications (PowerHap<sup>™</sup> and PiezoHapt<sup>™</sup>)

D. Matthew Reynolds EPCOS, Inc. A TDK Group Company PPD Business Group • Piezo Devices Santa Clara, CA September 17, 2018

### We provide a comprehensive product portfolio **Piezo & Protection Devices**

- Piezo actuators
- Piezo commodities
- PTC thermistors
- Inrush current limiters
- Disk varistors
- Multilayer varistors
- Multilayer NTC thermistors
- Surge arresters
- Switching spark gaps
- Ceramic ripple suppressors (CeraLink<sup>™</sup> capacitors)
- Toner sensors
- Electric surface potential sensors
- Multilayer HF packages
- Die-sized SAW packages

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### **TDK Piezo Product Portfolio and Applications**



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### Haptic feedback – Unlimited potential application



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### 2 types of haptic feedback usage

	Feedback to an area stroked with a fingertip	Feedback for pushing buttons
		100           100
Response	Pleasant response matching fingertip's sensitivity	Clear and strong response
	Smartphone display	

### **Piezo Haptic Product Lineup**

**PowerHap** and **PiezoHapt L** are both based on advanced multi-layer piezo ceramics technology. **PiezoHapt S** however is based on a single layer monolithic piezo ceramic disk.



### Why piezo as actuator?

#### ERM

#### **Eccentric rotating mass**



#### • Long response time

- Only sine waves
- Large
- No sensing functionality
- Low driving voltage
- High power consumption

#### LRA

#### Linear resonant actuator



- Medium response time
- Large
- No sensing functionality
- Low driving voltage
- Medium power
- consumption

#### **Piezo-based solutions**

#### Monolithic piezo discs



#### **Piezo bender**



#### • Thin

- Flexible wave design
- Short response time
- Sensing functionality
- Low power consumption
- High power

### Piezo effect: Sensor and actuator in <u>one</u> device



Source: https://commons.wikimedia.org/w/index.php?curid=17309925

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#### Ideal sensor for haptic applications



PowerHap<sup>™</sup> combines actuator and sensor in a single component

#### Piezo type vs electromagnetic type

ピエゾ (ビ歌) 式 / PiezoHapt*** L         PiezoHapt*** S         CERM         LRA           PowerHap***         PiezoHapt*** L         PiezoHapt*** S         ERM         LRA           Image (G) Acceleration (20g mass)         1.2 - 2.4         0.30 / 0.35         0.26         3         3           Image (G) Acceleration (20g mass)         8 - 65         1.6 / 1.5         4         2         5           Image (G) Acceleration (20g mass)         <1         <1         <1         50         20           Image (G) Acceleration (20g mass)         60 - 120         12/24         400         3         3           Image (G) Acceleration (20g mass)         60 - 120         12/24         400         3         3           Image (G) Acceleration (20g mass)         Yes         Yes         Yes         No         No									
PowerHap***         PiezoHapt**L         PiezoHapt**S         ERM         LRA           Image Set Set Set Set Set Set Set Set Set Se		ピエゾ (圧電) 式 / Piezoelectric 電磁式 , Electromag							
Image:		PowerHap™	PiezoHapt™ L	PiezoHapt™S	ERM	LRA			
<b>FpA [mm]</b> Thickness         1.2 - 2.4         0.30 / 0.35         0.26         3         3 <b>MEER [G]</b> Acceleration (20g mass)         8 - 65         1.6 / 1.5         4         2         5 <b>D</b> 5 L 5 0 [ms] Rise time         <1		<b>C</b> 3		0					
MEER [G] (20g mass)8 - 651.6 / 1.5425Dest LMD [ms] Rise time<1	厚み [mm] Thickness	1.2 - 2.4	0.30 / 0.35	0.26	3	3			
立ち上がり[ms]       <1	加速度 [G] <sup>Acceleration</sup> (20g mass)	8 - 65	1.6 / 1.5	4	2	5			
雷圧 (max.) [V]         60 - 120         12/24         400         3         3           自由な波形デザイン Custom waveform         Yes         Yes         Yes         No         No           感圧 Force sensing         Yes         Yes         Yes         Yes         No         No	立ち上がり [ms] <sub>Rise time</sub>	<1	<1	<1	50	20			
自由な波形デザイン Custom waveformYesYesYesNo感圧 Force sensingYesYesYesNo	電圧 (max.) [V] Drive voltage	60 - 120	12/24	400	3	3			
感E Force sensing Yes Yes Yes No No	自由な波形デザイン Custom waveform	Yes	Yes	Yes	No	No			
	感圧 Force sensing	Yes	Yes	Yes	No	No			

- Small and thin. Good integration with flat panel.
- Generate various vibration.
- Fast response. Force and frequency can be adjusted individually.
- Responds to complex waveform design without delay.

#### Our solutions: PiezoHapt<sup>™</sup> and PowerHap<sup>™</sup>

**PowerHap** and **PiezoHapt L** are both based on advanced multi-layer piezo ceramics technology. **PiezoHapt S** however is based on a single layer monolithic piezo ceramic disk.

## With this comprehensive product offering TDK is able to serve the complete market with piezo based actuators for active haptic solutions.



#### PiezoHapt<sup>™</sup> S

#### **Key Infos**

#### USP: "Cost effective solution!"

- $\rightarrow$  Sample available for both types
- $\rightarrow$  SOP : TBD
- → Automotive qualification to be acquired in 2019

#### **Target Applications (Examples):**

- Automotive
  - Steering wheel switches
  - Overhead consoles' switches
  - Touchpads
- Industry
  - Switches
  - Touchpads
- Consumer
  - Home appliance switches
  - PC trackpads
  - Remote control buttons



#### \*400V with Aito system

#### Remark

For optimal operation of this actuator, use of AitoChip is strongly recommended.

### PiezoHapt<sup>™</sup> L

#### Key Infos

#### USP: "Ultra thin!"

- → L8060 (General use): Sample available
- $\rightarrow$  L3015 (General use): Sample available
- $\rightarrow$  Automotive grade sample: TBD
- → SOP: Y2018 (L8060/General) Y2018 (L3015/General)

#### **Target Applications (Examples):**

- Automotive
  - Navigation system displays
  - Touchpads
- Industry
  - Control panels
- Consumer
  - Smartphones, tablets & wearable devices
  - Game console displays & controllers





### Ultra-thin actuator for haptic feed back



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### **Comparison of ERM and TDK PiezoHapt™ actuator**



### **PiezoHapt™ vibration mode can excite a large area.**

### **PiezoHapt<sup>™</sup> (L) overview**

PiezoHapt<sup>™</sup> (L) is a thin-type vibration unit consisting of a multi-layered piezoelectric element and a vibration plate.

#### POINT 1

Driven with low voltage and transmits tactile sensation to wide area

#### POINT 2

Delivers various kinds of vibration patterns since amplitude and frequency can be freely changed by pulse control





Ultra-thin Quick response Low drive voltage Quiet

30 x 15 x t 0.30 mm

80 x 60 x t 0.35 mm



### PowerHap™



Key infos	Product range						
JSP: "Powerful but thin!"	15G type			7G ty	pe	2.5G type	
Samples available Release and SOP early 2018 Release based on AEC-Q200			1	C			
arget applications (examples)	Piezo Cyn ceramics (bot	nbal p h sides)	Contact bads				
Automotive Displays	26 mm x 26 mm Thickness: 2.4 mm			12.7 mm Thickness: 1	x 12.7 mm	9 mm x 9 mm Thickness: 1.2 mm	
<ul> <li>Iouch pads / buttons</li> </ul>	Product	Acceleration		Voltage	Capaci-tance	Max. Dis-	T <sub>op,max</sub>
naustry Human machine interface	Specification	20gr. 100gr.	100gr.			placement	
<ul> <li>Building automatization</li> </ul>	<b>PowerHap 15G</b> Z63000Z2910Z 1Z 4	65G	15G	120V	3.6µF	200µm	85°C
<ul> <li>Mobile devices</li> </ul>	<b>PowerHap 7G</b> Z63000Z2910Z 1Z 5	30G	7G	120V	0.9 µF	65µm	85°C
<ul> <li>Game controllers</li> </ul>	<b>PowerHap 2.5G</b> Z63000Z2910Z 1Z 2	8G	2.5G	60V	0.8 µF	35µm	85°C

The cymbal acts as a lever to convert the contraction of the x- and y-axes into amplified displacement in the z-axis.

### **PowerHap™: Construction**



Piezo actuator	2.5G type	7G type	15G type							
Footprint [mm]	9.0 x 9.0	12.7 x 12.7	26.0 x 26.0							
Insertion height [mm]	1.2	1.9	2.4							
Operating voltage [V]	≤ 60	≤ 1	20							
Operating temperature [°C]	C] -40 °C to +85 °C									
Storage temperature [°C] -40 °C to +125 °C										
Displacement amplifier (cymbal)										
Sheet thickness [mm]	0.1	0.15	0.2							
Diameter [mm]	8.7	12.4	25.6							
Recess [mm]	0.2	0.26	0.5							
Axis of rotation symmetry Sheet Metal: 0.2 mm (E-Modulus 100 GPa)										
↓ 0.5 mm										
- MN										

Multilayer structure enables operation at low voltages.

### Acceleration vs. mass



### Two driving modes: Unipolar and bipolar





PowerHap<sup>™</sup>: Specified for two different driving modes Unipolar: Highest possible performance Unipolar means to drive PowerHap<sup>™</sup> from 0 V to the max. rated voltage (60 V for 2.5G type and 120 V for 7G and 15G types)

Bipolar: Much lower driving voltage Bipolar means to drive PowerHap<sup>™</sup> between +/-10 V for 2.5G type and +/-20 V for 7G and 15G types

# Different driving modes possible, depending on customer requirements.

#### Large displacement: Up to 200 µm





**Unipolar:** Elongation up to 30  $\mu$ m, 65  $\mu$ m and 200  $\mu$ m **Bipolar:** Elongation up to 15  $\mu$ m, 25  $\mu$ m and 85  $\mu$ m, respectively, for the 2.5G, 7G and 15G types

\*) Actuator is fixed on one side with vacuum; triangular pulses up to  $U_{max}$ ; t = 10 s

Large displacement range enables stimulation of all human mechanoreceptors for both driving modes.



### PowerHap<sup>™</sup>: Superior to all conventional haptic technologies

PowerHap™									
Size x, y, z [mm]	<b>2.5G</b> 9 x 9 x ()	type 1.2 mm	<b>7G</b> 12.7 x 12.7	<b>type</b> 7 x 1.9 mm	<b>15G type</b> 26 x 26 x 2.4 mm				
Voltage [V]	0 60	+/-10	0 120	+/-20	0 120	+/-20			
Acceleration [g] (20 g mass)	8 6		30	13	65	28			
Acceleration [g] (100 g mass)	2.5 1.5		7	2.5	15	7			
Elongation [µm]	30	15	65	25	200	85			
Energy per click [mJ]	1	0.1	3	0.4	8	1.0			
Custom waveforms	YES								
Force sensing			YE	ES					
The bipolar driv	ving mode	noode 80%	loss onora	v por click	compared				

The bipolar driving mode needs 80% less energy per click compared to the already very low energy consumption in unipolar driving mode.

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### Active haptic feedback for larger LCD displays









### "Lateral movement"

Actuator aside the display



### Lateral movement: Requirements for the actuator



#### Has to be mounted at the side of the display:

- $\rightarrow$  Can be long
- → Small in other dimensions

#### **Displays get larger and therefore more heavy**

→ Actuator needs to be "strong"

#### **Our solution: The 50G type**



### New 50G type



Contact surfaces	Piezo actuator	50G type		
both sides	Footprint [mm]	60 x 5.0		
sive	Insertion height [mm]	9.0		
	Operating voltage [V]	≤120		
mm	Operating temperature [°C]	-40 °C to +85 °C		
mmx9m	Storage temperature [°C]	-40 °C to +125 °C		
2 mm x 5 1.	Displacement amplifier (cymbal)			
60.	Sheet thickness [mm]	1.0		
	Length [mm]	59.0		
Multilayer piezo	Recess [mm]	2.6		
electrodes	MX			
0.000				
l lovout: 42 active lovore	MN.			
a layout. 43 active layers				
Multilayer structure ena	bles operation at relatively low voltage	ges.		

### Large displacement



Large displacement range enables stimulation of all human mechanoreceptors.

### **Strong force**



#### Short response time and high acceleration



Mass	100 g	500 g	1000 g
Acceleration [g]	50	10	5
Rise time [ms] *)		<1	
Power consumption per click [mJ]		10	

\*) Time between voltage switched on to vibration amplitude reaching 50% maximum G

#### Even weights above 1 kg can be accelerated and still create a good haptic feedback.

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### **PowerHap Minilateral**

Key Infos	Product range:						
<ul> <li>USP: "Small &amp; Powerful!"</li> <li>→ Low power consumption</li> <li>→ Supports force sensing</li> <li>→ Samples available</li> </ul>							
Target Applications (Examples):   Industry  Touchpads Control Panels Consumer	12mm Thickness: 2	NEW!NEW!12mm x 4mm9mm x 3.75mmvs:2.4mm1.8mm					
<ul> <li>Consumer</li> <li>Smartphones</li> <li>Tablets</li> <li>Keyboards &amp; Mice</li> </ul>	Product Specification	Acceler- ation 100gr.	Voltage Unipolar/ (bipolar)	Capacit- ance	Max. Displace- ment	T <sub>op,max</sub>	
<ul><li>Mobile devices</li><li>Game controllers</li></ul>	PowerHap Lateral 12x4 Z63000Z2910Z1 Z39	4.5G	60V / (±10V)	0.45µF	25µm	85°C	
	PowerHap Lateral 9x3.75 Z63000Z2910Z 1Z 41	3G	60V / (±10V)	0.32 µF	15µm	85°C	



### PowerHap<sup>™</sup> is superior to all conventional haptic technologies

	ERM Eccentric rotary mass	LRA Linear resonant actuators	Piezo benders	PowerHap™				
Size x, y, z [mm]	8x3x 3	Ø10x 3	3x4x 3	9x9x 1.2	12.7x12.7x 1.9	26x26x 2.4		
Acceleration [g] (20 g mass)	2	5	2.5	8	32	65		
Acceleration [g] (100 g mass)	0.6	1.7	0.65	2.5	7	15		
Rise time [ms]	50	25	10		<1			
Voltage	3	3	-100100	60	120			
Energy per click [mJ]	17	15	4	1	3	8		
Custom waveforms	No	No	Yes		Yes			
High-definition haptics	No	No	No		Yes			
Force sensing	No	No	No		Yes			
			4		C3			

# Piezo actuator adds the haptic dimension to a comprehensive range of HMIs





#### **Selection table**

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	Driving Voltage		Actu Thick	ator mess	Required Area (in mm)		Max. moveable weight > min. 3G acceleration				Automotive Qualification			
	24V	60V - 120V	>200V	<0.5mm	>1.2mm	9 x 9 - 12 x 12	12 x 12 - 15 x 15	30 x 15 - 30 x 30	80 x 60	<30gr.	30gr. - 100gr.	250gr.	1.000gr.	
PiezoHapt S φ15mm			X	X			X			X				
PiezoHapt S φ12mm			X	X		X				X				
PiezoHapt S φ15mm – Auto			X	X			X			X				X
PiezoHapt S φ12mm – Auto			X	X		X				X				X
PiezoHapt L L8060-General	X			X					X	X				
PiezoHapt L L8060 – Auto	X			X					X	X				X
PiezoHapt L L3015-General	X			X				X		X				
PowerHap 15G		X			X			X					X	X
PowerHap 7G		X			X		X					X		X
PowerHap 2.5G		X			X	X					X			X



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