

SmartIndustrial[™]

PRIMARY APPLICATIONS



Navigation

Maintain your vehicle or navigation unit in the right path over the full temperature range. IMU data is coupled with GNSS to constrain position and bridge GNSS outage.



Vibration Monitoring

Motors monitoring systems use vibration sensors to prevent down times and schedule maintenance at the right time.



Tilt Sensing for Construction Equipment

Whether it is for construction vehicles or electrical tools, an accurate tilt sensor is critical to securely operate most construction equipment.



Manufacturing & Robotics

Industrial robots use motion data to enable automation, improve efficiency, monitor conditions via the precise motion and vibration measurements produced.

FEATURED PRODUCTS

IIM-42630/4



23 × 23 × 8 mm³

High-performance fault tolerant 6-Axis IMU module that provides best in class bias instability and ARW at an affordable price

IIM-20670



4.5 × 4.5 × 1.1 mm³

Thermally Stable IMU for Drone & Stabilization Applications. The low VRE specification leverages the product for deployment in high vibration environment

IIM-42652/3



2.5 × 3 × 0.91 mm³

Compact 6-axis, high FSR (/3), configurable IMU that can withstand an extended operating temperature range while requiring very low power

IIM-42351/2



2.5 × 3 × 0.91 mm³

High-performance, Low-power Accelerometer with multiple capabilities to enable easy, robust and accurate tilt and vibration measurements



InvenSense, a TDK Group Company ("TDK InvenSense") is committed through its Product Longevity Program ("PLP") to ensure that its customers will have access to a stable supply of products for their designs. Products are selected for the PLP from products developed for automotive and industrial markets.

PRODUCT CATEGORIES

IIM-46230 & IIM-46234

High End Industrial, GNSS Module, Delivery Systems

- Best in class bias instability 1.9°/hr
- Ultra-low ARW = $0.09^{\circ}/\sqrt{(hr)}$
- Custom calibration to improve thermal stability
- Processing power to incorporate complex algorithms

IIM-20670

Antenna Stabilization, Drones

- Max Gyroscope FSR: ±1966 dps
- Max Accelerometer FSR: ±65g
- Good stability over temp
- · Low Vibration Rectification Error

IIM-42652 & IIM-42653

Autonomous Mobile Robots, Navigation Units, Drones

- High FSR 4000dps & 32g (IIM-42653 only)
- Good bias instability 3.8°/hr
- Low noise density 70μg

IIM-42351 & IIM-42352

Tilt Sensing, Construction Tools, Vibration Sensing (IIM-42352 only)

- 3-Axis Accelerometer
- High bandwidth up to 4 kHz (IIM-42352 only)

 $Note: All\ products\ have\ an\ Operating\ Temperature\ Range\ of\ -40^{\circ}C\ to\ 105^{\circ}C\ and\ a\ Shock\ Tolerance\ of\ 10,000g$

PRODUCT DETAILS

| Parameters | Units | IIM-46234 | IIM-46230 | IIM-20670 | | IIM-42653 |
|-----------------------------|----------|-------------|--------------------|-------------|------------|---------------------|
| | Axes | X, Y, Z | X, Y, Z | X, Y | Z | X, Y, Z |
| | LxWxH3 | 23 x 23 x 8 | 23 x 23 x 8 | 4.5 x 4.5 x | 1.1 | 2.5 x 3 x .91 |
| Output Data Rate (Max ODR) | kHz | 1 | 1 | 8 | | 32 |
| Gyro FSR | dps | ±480 | ±250/500/1000/2000 | ± 41, 61 | 1311, 1966 | ±500/1000/2000/4000 |
| Gyro Noise Density | mdps/√Hz | 1.6 | 3 | 5 | | 3.8 |
| Gyro Bias instability | deg/H | 1.9 | 4.1 | 13 | | 3.6 |
| Gyro Bias over Temp | mdps/C ± | 0.966 | 2.069 | 1.724 | | 10 |
| Gyro Sensitivity Over Temp | %/C ± | 0.001 | 0.001 | 0.001 | | 0.005 |
| Angular random walk | deg/√hr | 0.07 | 0.15 | 0.23 | | 0.15 |
| Gyro Non-Linearity | %FS ± | 0.04 | 0.046 | 0.2 | | 0.1 |
| Accel FSR | g | ±8 | ±2/4/8/16 | ±2/4/8/16 | /32/64 | ±2/4/8/16/32 |
| Accel Bias repeatability | mg ± | 0.2 | 0.4 | 1 | | 20 |
| Accel Noise Density | μg/√Hz | 29 | 41 | 172 | 248 | 70 |
| Accel Bias Over Temp | ug/C ± | 6.9 | 13.8 | 3.5 | 138 | 150 |
| Accel Sensitivity Over Temp | %/C ± | 0.001 | 0.001 | 0.001 | 0.003 | 0.005 |
| Accel Non-Linearity | %FS ± | 0.05 | 0.05 | 1 | | 0.1 |



Scan Here

for additional materials and information.